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Revisions on
Development and Application of the Finite Element Method based on MATLAB.

The following corrections must be considered:

- Page 12 - Eqn. (2.5): transposition of matrix
With respect to a general representation, it might be better to formulate

$$\mathbf{T}^* = \mathbf{Q}^T \cdot \mathbf{T} \cdot \mathbf{Q} .$$

But be careful with some implementations, e.g. the ABAQUS internal *eigenvalue solver* SPRIND, which results in the transposed matrix structures as given before.

- Page 16 - Eqn. (2.20) and (2.21): '-'-sign and indices

$$\begin{aligned} I_2(\mathbf{C}) = I_2(\mathbf{b}) &= \frac{1}{2} [(\text{trace } \mathbf{C})^2 - \text{trace } \mathbf{C}^2] \\ &= \text{trace } \mathbf{C}^{-1} \det \mathbf{C} = \lambda_1^2 \lambda_2^2 + \lambda_1^2 \lambda_3^2 + \lambda_2^2 \lambda_3^2 \end{aligned}$$

Please excuse all associated inadequacies. For further notes I am very grateful !
H. Baaser